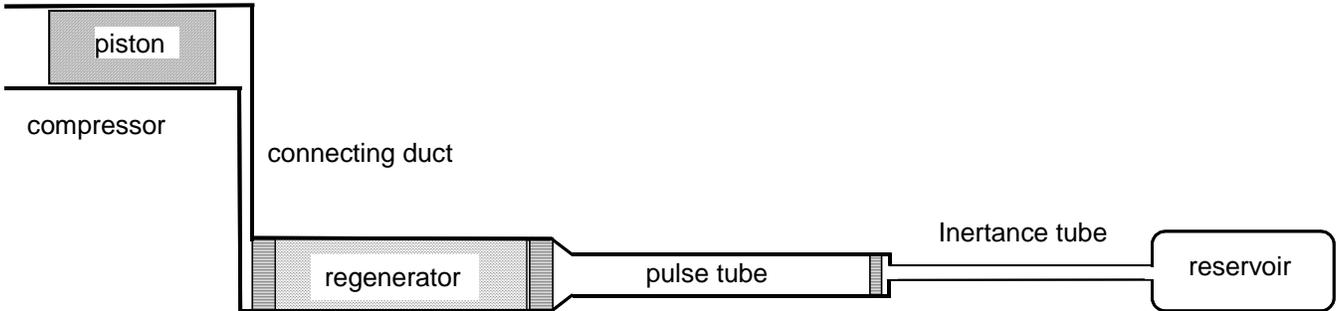


# Sage Model Notes

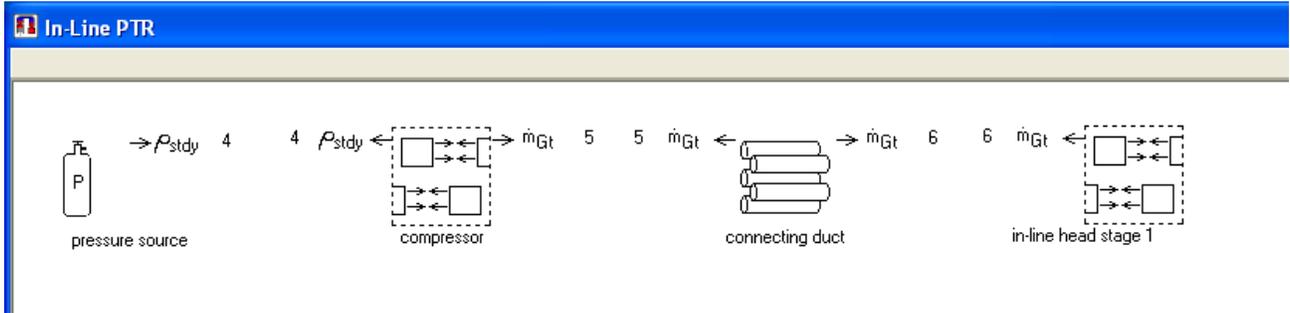
## InLinePTR.ptb

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A model for a single-stage pulse-tube cooler with pulse-tube arranged in-line with regenerator. Similar to the CoAxPTR model without so many geometrical constraints. Here is a rough schematic of the physical layout:

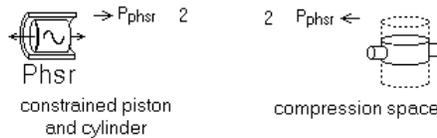


At the top-level the Sage model consists of a compressor submodel and a cold-head submodel with a connecting duct between the two:



## Compressor

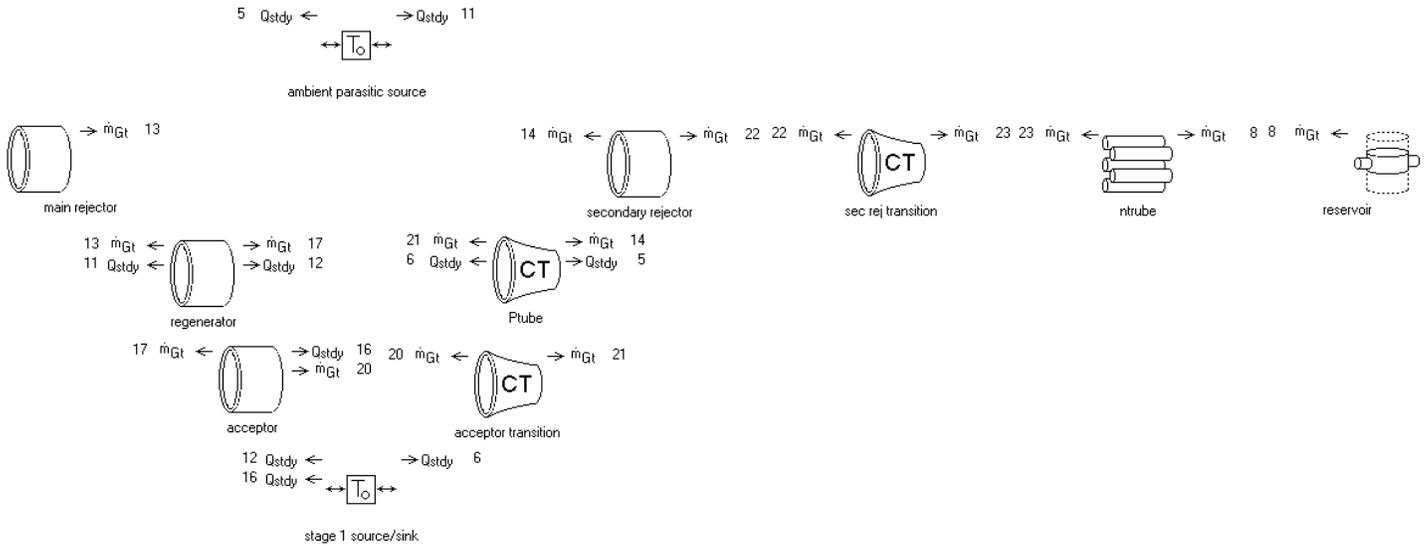
The compressor consists of a single constrained piston driving a compression space:



Within the *constrained piston and cylinder* component there is a constrained piston with an area attachment connected to the compression space. That area  $A$  is an independent input by default but in this case recast to  $0.25 \cdot \pi \cdot D_{shell}^2$  so it automatically adjusts to the piston diameter  $D_{shell}$  input of the *constrained piston and cylinder*.

# Cold Head

Within the cold head (*in-line head stage 1*) are a number of components that simulate a in-line pulse-tube arrangement. The reason for the naming 'stage 1' is to anticipate the possibility of copying the entire submodel and pasting it back into the model to implement a higher stage.



The components are ordered in rows of decreasing temperature downward and horizontally in order of their physical layout. The *main rejector*, *acceptor* and *secondary rejector* components house copper heat-exchanger screens. The *regenerator* component houses a random-fiber regenerator. The *Ptube* component represents a tapered pulse tube while the *acceptor transition* and *sec rej transition* components represent minor transitional volumes. The *nrtube* and *reservoir* components model an intertance-tube phase shifter terminated by a fixed volume reservoir.

The *ambient parasitic source* anchors only parasitic wall thermal conductions. The *stage 1 source/sink* anchors wall conductions as well as cooling-power via conduction to the *acceptor* heat exchanger.

Were this part of a two-stage model there would be another positive facing  $\dot{m}_{Gt}$  connector created as a positive gas inlet within the gas sub-component of either the *acceptor* or *acceptor transition*. This connector would be promoted up to the root model level for connection to the *main rejector* of the second stage, thereby representing a pneumatic connection between the first and second stages.

There are a number of user-defined inputs and outputs at the submodel level:

## Inputs

ODregen	regenerator matrix OD (m)	2.000E-02
IDptube	pulse tube ID (m)	1.200E-02
IDnrtube	inertance tube ID (m)	3.500E-03

## Outputs

QrejColdhead1	net rejection to ambient	6.371E+01
Qlift1	first stage net lift	3.509E+00

The following Lower-level components have their inputs recast in terms of the above inputs.

#### **main rejector**

Canister ID is recast to equal the regenerator matrix diameter  $OD_{regen}$ . The *conductive surface* sub-component models radial heat flow through the wires. It has input  $D$  recast to half the canister radius ( $0.25 * D_{in}$ ).

#### **regenerator**

Canister ID is recast to equal the regenerator matrix diameter  $OD_{regen}$ . The outer wall of the regenerator canister represents the pressure wall which is important for modeling thermal conduction loss.

#### **acceptor**

Canister ID as well as conductive surface  $D$  are recast as for the *main rejector*. There is also a solid conduction path to the *stage 1 source* temperature. This conduction path (*wall distributed conductor*) simulates a copper cylinder wall thermally bonded to the screens. Its input  $D$  is recast to the wall thickness  $W_{can}$  inherited from the *acceptor* canister.

#### **acceptor transition**

This is an optional component designed to model a possible transition volume between acceptor heat exchanger and pulse tube. It is a tapered tube with diameter as a function of position defined by cubic spline interpolation pairs. The diameter at the negative endpoint is recast to  $OD_{regen}$  and at the positive endpoint to  $ID_{ptube}$ . It has an adiabatic wall so that all cooling heat transfer takes place in the *acceptor* heat exchanger.

In reality the flow in such a transition likely to be non-uniform, undeveloped, even separated. All of which lie beyond the scope of the Sage 1-D model to resolve. So don't expect extreme accuracy of this component. It is mainly present to account for the volume of the transition.

#### **Ptube**

This is another tapered tube component with diameters defined by cubic spline interpolation pairs. The diameter at the negative endpoint, mid-point and positive endpoint are all recast to  $ID_{ptube}$ . Recasting to separate diameters would also be possible to represent a tapered pulse tube.

Accurate modeling of this component requires that the incoming flow at either end be uniformly distributed without any high velocity jets or other flow separations.

#### **secondary rejector**

Canister ID is recast to  $ID_{ptube}$ . Conductive surface  $D$  is recast as for the *main rejector*.

#### **sec rej transition**

Another optional transition component, this time modeling a transition volume (possibly a conical flow diffuser) between secondary rejector and inertance tube. It is a tapered tube component with diameters defined by cubic spline interpolation pairs. The diameter at the negative endpoint is recast to  $ID_{ptube}$  and at the positive endpoint to  $ID_{nrTube}$ . It has an isothermal wall surface with heat rejected to that surface monitored by user-defined output  $Q_{srTrans1}$ .

### **nrtube**

A single tube with ID recast to IDnrtube representing an intertance-tube phase shifter. Sort of like a  $\frac{1}{4}$  wave open-ended organ pipe with the open end being the end connected to the *reservoir*.

## **Cold Temperature**

The file is currently set up for a cold-end temperature of 70K. To change cold-end temperature change the  $T$  input for the *stage 1 source/sink*, which establishes the acceptor screen temperature by solid conduction. Also, you might want to change Tinit at the positive end of the regenerator and negative end of the pulse-tube. These changes are not strictly necessary because the regenerator and pulse-tube temperatures are solved, with Tinit only providing initial values.

## **Bottom-Line Outputs**

Net cooling power is available in the *in-line head stage 1* submodel user-defined variable  $Qlift1$ . It derives from the net heat leaving the *stage 1 source/sink* component — the heat flow absorbed by the helium in the *acceptor*, less the conduction losses down the regenerator and pulse-tube canisters.

Compressor PV power input is available in user variable  $Wpv$  in the *compressor* submodel. There is no model of the motor driving the compressor piston so electrical power input is not available.

## **Optimization**

The model contains a rudimentary optimization specification. The objective is to maximize net cooling power  $Qlift1$ , subject to compressor PV power equal to 100 W ( $Wpv = 100$ ). Optimized variables are compressor piston amplitude  $Xamp$ , regenerator matrix  $Porosity$  and intertance tube  $Length$ .

Also optimized is the stiffness  $K$  of the spring attached to the compressor piston in order that the required force provided by the drive motor ( $FF$ ) be in phase with the piston motion ( $FF.Real = 0$ ).

This optimization is intended as a starting point for more serious design optimizations.